## 1398073 <br> BNMI-013

No. of Printed Pages : 5

# BACHELOR OF ARTS IN 3D ANIMATION AND VISUAL EFFECTS (BAAVFX) 

Term-End Examination
June, 2019
BNMI-013 : MATCH MOVING

> Time : $1 \frac{1}{2}$ Hours
> Maximum Marks : 30

Note : Attempt all questions.

## Section-A

Note : The following Section has objective questions. Select the right answers. Each question carries 1 mark.

1. Which one of the following is not a principal of an animation?
(a) Are
(b) Appeal
(c) Bouncing Ball
2. Dope sheet is known as $\qquad$
(a) X -sheet
(b) Y-sheet
(c) Z-sheet
3. Most natural action tends to follow a/an trajectory.
(a) Flat
(b) Linear
(c) Arched
4. In graph Editor, Linear Tangents give $\qquad$
(a) Ease In, Ease out motion
(b) Straight In, Ease out motion
(c) Straight In, Straight out motion
5. Timing refers to the number of drawings or frames for a given action.
(a) True
(b) False
6. Adding .............. to the main action gives a scene more life, and can help to support the main action.
(a) Parallel actions
(b) Secondary actions
(c) Alternative actions
7. A point constraint causes an object to move to and follow the position of an object, or the position of several objects.
(a) additive
(b) collective
(c) average
8. .............. animation is a way of animating an object's translation and rotation attributes by specifying a NURBS curve as the object's trajectory.
(a) Curve
(b) Spline
(c) Path
9. 

animation lets you split, duplicate and blend animation elips to achieve the motion effects that you want.
(a) Non-linear
(b) Pose to Pose
(c) Linear
10.
............. are hierarchical, articulated structures that let you pose and animate bound models.
(a) Bipeds
(b) Skeletons
(c) Joints
11. When a model is bound to a skeleton using ..........., it then follows or reacts to the transformations of the skeleton's joints and bones.
(a) Skinning
(b) Linking
(c) Binding
12. ............. constraints cause the constrained object to inherit the transformations and global orientation of its target objects.
(a) Aim
(b) Geometry
(c) Parent
13. Every skeleton has several parent joints, child joints and one $\qquad$
(a) dummy
(b) root
(c) proxy
14.
.......... are useful for creating detailed arcing movements, but not very intuitive for goaldirected movements.
(a) Reverse kinematics
(b) Inverse kinematics
(c) Forward kinematics
15. You can use deformers as modeling tools.
(a) True
(b) False

## Section-B

Answer the following questions in brief. Each question carries 5 marks.
(i) Explain the following constraint with example (any $t w o$ ) :
(a) Seale
(b) Parent
(c) Aim
(ii) Explain the skin deformer and its uses.
(iii) Explain the following Animation Principles with examples (any two) :
(a) Staging
(b) Anticipation
(c) Secondary Action

