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BIEL-020

B.Tech. – VIEP – ELECTRONICS AND COMMUNICATION ENGINEERING (BTECVI)

DD655 Term-End Examination June. 2019

BIEL-020 : CONTROL ENGINEERING

Time : 3 hours

Maximum Marks : 70

- Note: Attempt any seven questions. All questions carry equal marks. Use of scientific calculator is permissible. Use of graph paper and semi-log sheet is allowed.
- 1. (a) What is the use of feedback in control systems to parameter variations ?
 - (b) Consider the following transfer function :

$$G(s) = \frac{(s+2)(s+1)}{s(s+5)(s+3)(s+7)}.$$

Draw pole-zero plot, s plane is considered upto infinity.

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 For the block diagram shown in Figure 1, determine the overall transfer function.



Figure 1

 Draw the signal flow graph and determine C/R for the block diagram shown below.
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Figure 2

 Define position, velocity and acceleration error constant. Explain how these error constants are useful in finding steady state error with an example.

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5. Open loop transfer function of a certain unity feedback system is

$$G(s) = {k(s+1) \over s(s-1)(s+6)}$$

Determine :

- (a) The range of value of k for which the system is stable.
- (b) The value of k that will result in the system being marginally stable.
- 6. Plot the root locus pattern of a system whose forward path transfer function is

$$G(s) = \frac{k}{s(s+2)(s+3)}.$$
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- 7. Explain how to determine gain margin and phase margin of a closed loop control system for its root loci. Illustrate with the help of an example. 10
- 8. (a) What is closed loop transfer function of a system with positive feedback ? Explain the effect of positive feedback on stability.
 - (b) Discuss the advantages and limitations of frequency response method of analysis for control systems.

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- **9.** (a) Explain frequency response analysis in control systems.
 - (b) Explain polar and inverse polar plot. What is the role of these plots in control systems?
- **10.** Apply Nyquist stability criterion to the system with loop transfer function

G(s) H(s) =
$$\frac{(4s+1)}{s^2(s+1)(2s+1)}$$

and ascertain its stability.

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