

**DIPLOMA IN ELECTRICAL ENGINEERING
(DELVI) / ADVANCED LEVEL CERTIFICATE
COURSE IN ELECTRICAL ENGINEERING
(ACELVI)**

00834

Term-End Examination

June, 2014

**BIEE-030 : INDUSTRIAL DRIVES AND
CONTROLS**

Time : 2 hours

Maximum Marks : 70

Note : Attempt any **five** questions. All questions carry equal marks. Question no. 1 is **compulsory** (objective type). Draw neat and clean diagrams, if any required.

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1. Attempt all objective type questions : 7×2=14
- (a) Armature voltage of a DC motor can be controlled by means of
- (i) Cyclo converter
 - (ii) Inverters
 - (iii) AC-DC converter
 - (iv) Bridge rectifier with fixed input
- (b) The speed of DC shunt motor above normal speed can be controlled by
- (i) Armature voltage control method
 - (ii) Field current control method
 - (iii) Both methods
 - (iv) None of these

- (c) For controlling the speed of DC motor of 150 HP rating, the following type of converters are normally used.
- (i) Single phase full converters
 - (ii) Single phase dual converters
 - (iii) Three phase full converters
 - (iv) Three phase dual converters
- (d) A DC chopper circuit controls the average voltage across the DC motor by
- (i) Controlling the input voltage
 - (ii) Controlling the field current
 - (iii) Controlling the line current
 - (iv) Continuously switching ON and OFF the motor for fixed durations of t_{ON} and t_{OFF} respectively
- (e) A motor armature supplied through phase-controlled SCR's receives a smoother voltage shape at
- (i) high motor speed
 - (ii) low motor speed
 - (iii) rated normal motor speed
 - (iv) None of these
- (f) For controlling the speed of a three-phase induction motor, the method generally used is the
- (i) fixed voltage fixed frequency method
 - (ii) variable voltage variable frequency method
 - (iii) fixed voltage variable frequency method
 - (iv) variable voltage fixed frequency method

- (g) Variable speed drives using stator voltage control are normally
- (i) open loop system
 - (ii) closed loop system
 - (iii) both are correct
 - (iv) both are incorrect
2. (a) Explain how a thyristor bridge can be used for speed control DC shunt motor.
- (b) List out the applications of phase control converters. 7+7=14
3. (a) Explain the working principle of a single phase full wave half controlled bridge rectifier using two SCR's and two diodes.
- (b) Draw and explain the connection diagram of three phase full wave half controlled rectifier bridge. 7+7=14
4. (a) What is a DC chopper ? Give various types of chopper configurations with appropriate figures.
- (b) Explain the Regenerative and Rheostatic braking mode of chopper drives. 7+7=14
5. (a) Discuss the speed control of single phase separately excited DC motor.
- (b) Draw the waveform of voltage and current for semi-converter series motor drive. 7+7=14

6. (a) Compare CSI and VSI fed drives.
- (b) Discuss briefly the different methods for controlling the speed of wound rotor induction motors. 7+7=14
7. (a) Discuss briefly the various methods of speed control of 3-phase cage rotor and induction motor.
- (b) Draw the circuit of stator voltage control of delta connected induction motor using closed loop method. 7+7=14
8. Write short notes on any **four** of the following : $4 \times 3 \frac{1}{2} = 14$
- (a) Advantages and disadvantages of Thyristorised Drives
- (b) Two quadrant operation for DC motor
- (c) Speed regulation by armature voltage control
- (d) Speed regulation by armature current control
- (e) Electric braking of motors
- (f) Block diagram of closed loop operation of induction motor
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