

**B.Tech. – VIEP – ELECTRONICS AND
COMMUNICATION ENGINEERING
(BTECVI)**

00334

Term-End Examination

June, 2014

BIEL-020 : CONTROL ENGINEERING

Time : 3 hours

Maximum Marks : 70

Note : Attempt any *seven* questions. All questions carry equal marks. Use of calculator is permissible.

1. (a) Find the transfer function of the signal graph shown in Figure 1. 5

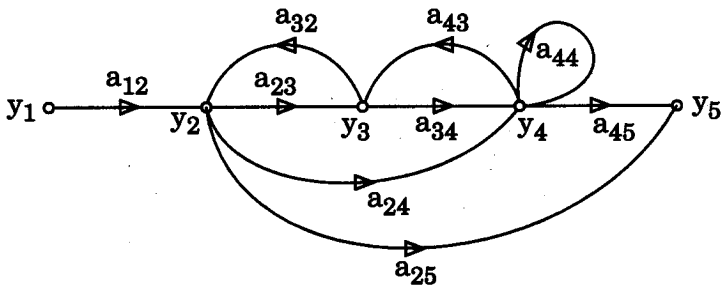
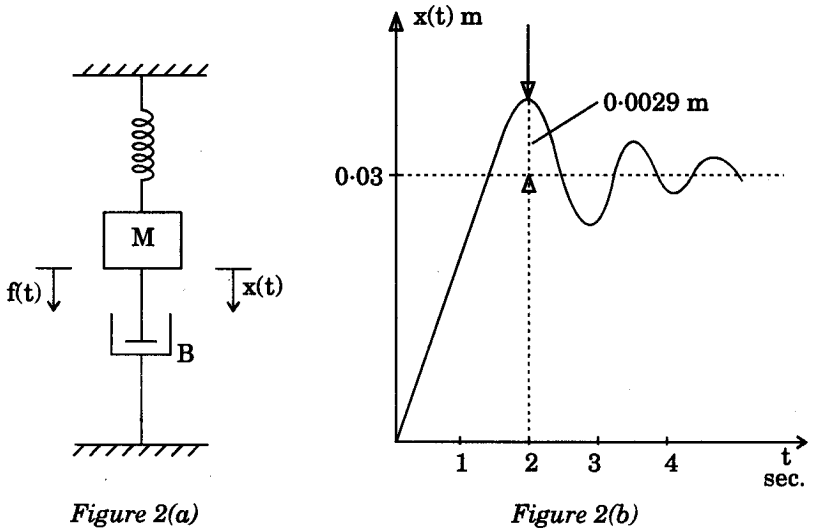


Figure 1

- (b) What is the effect of feedback on the system gain and system sensitivity ? Prove it mathematically. 5

2. A mechanical vibratory system is shown in Figure 2(a). When a force of 8.9 N is applied to the system, the mass oscillates as shown in Figure 2(b). Find the values of M, B and K. 10



3. (a) What is meant by PID control? What are the advantages of PID controller? 4
- (b) The forward path transfer function of a unity feedback control is given by

$$G(s) = \frac{2}{s(s+3)}$$

Obtain the expression for unit step response of the system. 6

4. The characteristic equation of a feedback control system is $s^4 + 20s^3 + 15s^2 + 2s + K = 0$.

(a) Determine the range of K for the system to be stable. 4

(b) Can the system be marginally stable? If so, find the required value of K and the frequency of sustained oscillation. 6

5. Draw the Bode plot for the transfer function

$$G(s) = \frac{36(1 + 0.2s)}{s^2(1 + 0.05s)(1 + 0.01s)}$$

From the Bode plot, determine

- (a) Phase Crossover frequency
- (b) Gain Crossover frequency
- (c) Gain Margin
- (d) Phase Margin 10

6. Sketch the polar plot of the function

$$G(s) = \frac{1}{s^2(1 + sT)} \quad 10$$

7. State and explain the Nyquist Stability Criterion.

What is the effect of addition of a pole at $s = 0$ to $G(s)H(s)$ on the Nyquist plot? 10

8. What is lag-compensator ? Obtain the transfer function of lag-compensator and draw the pole-zero plot. 10
9. Obtain the state variable representation of a field-controlled dc motor shown in Figure 3. 10

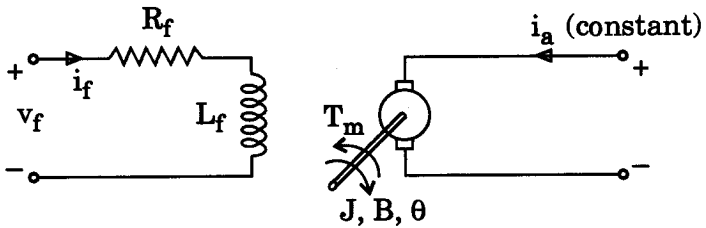


Figure 3

10. Write short notes on any *two* of the following : $2 \times 5 = 10$
- (a) Neural Network
 - (b) Routh-Hurwitz Stability Criterion
 - (c) M and N Circle