

**B.Tech. IN ELECTRONICS AND
COMMUNICATION ENGINEERING
(BTECVI)**

Term-End Examination

June, 2012

BIEL-007 : SIGNALS AND SYSTEMS

Time : 3 hours

Maximum Marks : 70

Note : Attempt any seven questions. All questions carry equal marks. Use of Scientific calculator is allowed . All the questions are to be answered in English language only.

1. Determine whether or not the signals below are periodic, and for each signal that is periodic, determine the fundamental period : 10

(a) $x[n] = \cos\left(\frac{2\pi n}{5}\right) + \cos\left(\frac{2\pi n}{7}\right)$

(b) $x[n] = \cos\left(\frac{n}{10}\right) \cos\left(\frac{n\pi}{10}\right)$

(c) $x(t) = 2 \cos 100\pi t + 5 \sin 50t$

(d) $x[n] = e^{(j\pi/16)n} \cos\left(\frac{n\pi}{17}\right)$

(e) $x(t) = 10 \cos^2(10\pi t)$

2. The impulse response of LTI system is given below. Check whether the following systems are memory less, stable and causal 10

(a) $h(t) = e^{-2t}u(t-1)$

(b) $h(t) = e^{-4t}u(t+10)$

(c) $h(t) = te^{-t}u(t)$

(d) $h(n) = n \left(\frac{1}{2} \right)^n u(n)$

(e) $h(n) = 2u(n) - 2u(n-5)$

3. (a) Determine and sketch the convolution of the following two signals : 5

$$x(t) = \begin{cases} t+1, & 0 \leq t \leq 1 \\ 2-t, & 1 < t \leq 2 \\ 0, & \text{elsewhere} \end{cases}$$

and $h(t) = \delta(t+2) + 2\delta(t+1)$

- (b) Show that the convolution of an odd and an even function is an odd function. 5

4. Find the transfer function of a causal continuous time LTI system described by differential equation 10

$$\frac{d^2y(t)}{dt^2} + 5\frac{dy(t)}{dt} + 6y(t) = s(t)$$

With the initial conditions assume to be zero. Also, find the response of the system to input $s(t) = 2u(t)$

5. Find the trigonometric Fourier series for the wave form shown in Fig.1 10

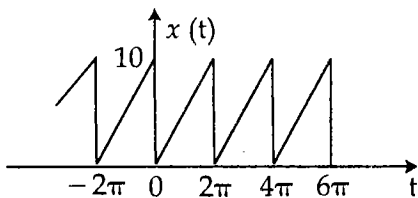


Fig. 1 Aperiodic signal

6. (a) Determine the Fourier Transform (CTFT) of the signal 5

$$x(t) = \frac{1}{2} \left[\delta(t+1) + \delta(t-1) + \delta\left(t + \frac{1}{2}\right) + \delta\left(t - \frac{1}{2}\right) \right]$$

- (b) Find the continuous time Fourier transform of the following : 5

$$x(t) = \begin{cases} \frac{At}{t_p - t_Q} + \frac{At_p}{t_p - t_Q}; & \text{for } -t_p < t < -t_Q \\ A; & \text{for } -t_Q < t < t_Q \\ \frac{At_p}{t_p - t_Q} - \frac{At}{t_p - t_Q}; & \text{for } t_Q < t < t_p \end{cases}$$

7. Determine the inverse Z - transform of the function. 10

$$x(z) = \frac{Z^2}{Z^2 - \left(\frac{5}{4}\right)Z + \frac{3}{8}}$$

8. Find the Z - transform of the following discrete - time signal. Also determine the ROC for each of the following. 10

(a) $S(n) = 2^n u(n) + 3 \left(\frac{1}{2}\right)^n u(n)$

(b) $S(n) = 3 \left(-\frac{1}{2}\right)^n u(n) - 2(3)^n u(-n - 1)$

9. For the discrete time system described by the following difference equation. 10

$$y(n) = 0.6y(n - 1) - 0.08y(n - 2) + x(n)$$

Determine :

- (a) The unit -sample response sequence, $h(n)$
(b) The step - response sequence $g(n)$
(c) Whether it is BIBO stable.
10. Write short notes on *any two* : 5x2=10
- (a) Properties of Z - transform.
(b) Region of convergence (ROC).
(c) Linear time Invariant (LTI) system.
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