

**B.Tech. MECHANICAL ENGINEERING
(COMPUTER INTEGRATED MANUFACTURING) /
B.Tech. AEROSPACE ENGINEERING (BTAE)**

Term-End Examination

00105

December, 2014

BME-006 : MECHATRONICS

Time : 3 hours

Maximum Marks : 70

Note : Answer any **seven** questions. All questions carry equal marks. Use of scientific calculator is allowed.

1. (a) Identify the sensor, signal conditioner and display elements in the measurement system of a Bourdon pressure gauge. 5
- (b) Explain the difference between open- and closed-loop control system. 5
2. (a) Explain what is meant by sequential control and illustrate your answer by an example. 5
- (b) Compare and contrast the traditional design of a watch with that of the mechatronics-designed product involving micro-processor. 5

3. (a) Draw a block diagram of a basic micro-controller and explain the function of each subsystem. 5
- (b) What are the logic functions used for switches (i) in series and (ii) in parallel? 5
4. (a) Apply the Hurwitz-Routh criterion to determine the stability of the system whose characteristics equation is given by

$$s^5 + 6s^4 + 9s^3 - 4s^2 + 11s - 20 = 0.$$
 5
- (b) Find the inverse Laplace transforms of

$$\frac{s^2 - 3s + 4}{s^3}$$
 5
5. (a) How do you classify transducers? Describe the working of any one type of transducer. Also list out some industrial applications of transducers. 5
- (b) What is a sensor? Explain active and passive sensors. Also list out the basic requirements of sensors. 5
6. (a) A 6-bit D/A converter gives an output voltage of 17.250 volts for an input of 010111. What is the step size, the full range voltage and the percentage resolution? 5
- (b) Determine the octal equivalent of
 $(432267)_{10}.$ 5

7. (a) A double acting cylinder has a pressure of 40 bars acting on both sides. The cross-sectional areas of the two sides are 200 cm^2 and 100 cm^2 . Find out the net load against which the cylinder can operate. If a pressure compensated flow control valve is put in the return line which allows only a flow of 10 litre/min through it, at what speed will the cylinder move ? 5
- (b) Prove that the z-transform of a unit step function is $\frac{z}{z-1}$. 5
8. (a) A DC motor taken an armature current of 100 A at 480 V. The resistance of the armature circuit is 0.2Ω . The machine has six poles and the armature is lap connected with 864 conductors. The flux per pole is 0.5 Wb. Calculate the following : 5
- (i) The speed
- (ii) The gross torque developed by the system
- (b) Describe the basic principles of stepper-motors and servo-motors. 5
9. (a) Explain the working principle of relay with the help of a schematic diagram. 5
- (b) What do you mean by inverse kinematics ? Briefly explain the importance of path planning. 5

10. Write short note on any *five* of the following : $5 \times 2 = 10$

- (i) Digital-to-Analog Converter
 - (ii) Error Signal
 - (iii) Simulation
 - (iv) Bit
 - (v) Modem
 - (vi) Ladder Diagram
 - (vii) EPROM
 - (viii) Indicator Lamp
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