

**ADVANCED LEVEL CERTIFICATE COURSE IN
ELECTRICAL ENGINEERING/DIPLOMA IN
ELECTRONICS AND COMMUNICATION
ENGINEERING (DELVI/ACELVI)**

Term-End Examination

December, 2012

BIEE-028 : ELECTRICAL MACHINE THEORY-II

Time : 2 hours

Maximum Marks : 70

Note : Q No. 1 is *compulsory*. Attempt *any four* from Q 2 to Q 8. Each Question is of **14** marks. Use of scientific calculator is allowed.

1. (a) In a double cage induction motor, the inner cage has : **7x2=14**
- (i) Low R and Low X
- (ii) Low R and high X
- (iii) High R and high X
- (iv) High R and Low X
- (b) At low slip, Torque is directly proportional to slip S in a 3 phase induction motor. (T/F)
- (c) The ratio between rotor input, rotor output and rotor copper losses is 1: (1 - s) : S. (T/F)
- (d) A synchronous motor is said to be "floating" when it operates on no load and without losses. (T/F)

- (e) For under excited operation of a synchronous motor the p.f will be lagging. (T/F)
 - (f) In alternator, field winding is on stator. (T/F)
 - (g) Steam turbine has normally high rotating speed. (T/F)
2. A 1000 kVA, 6.6 kV, 50 Hz, Y-connected synchronous generator has a no-load voltage of 11.4 kV at a certain field current. The generator gives rated terminal voltage at full load 0.75 lagging factor at the same field current. Calculate :
- (a) Synchronous reactance (armature resistance being negligible)
 - (b) Voltage regulation
 - (c) Torque angle
 - (d) Electrical power developed
 - (e) Voltage and kVA rating if generator is reconnected in delta.
3. (a) Why starters are necessary for starting induction motor ? 7
- (b) Name different starting methods of 3- ϕ induction motors. 7

4. Explain what is meant by stand still reactance of induction motor rotor ? How does it vary with speed ? **14**
5. (a) Give reasons for low efficiency of hysteresis and reluctance motors. **2x7=14**
(b) What is advantage of a capacitor start motor over a resistance split phase motor ?
6. (a) What is damper winding ? What is the function of it and where it is located ? **2x7=14**
(b) What is a distributed winding and what is distribution factor ?
7. (a) What are servomotors and list their characteristics ? **2x7=14**
(b) State the various applications of a stepper motor.
8. Attempt *any four* of the following. Write short notes on : **4x3.5=14**
(a) Power flow diagram of an induction motor.
(b) Cause of low power factor of induction motors.
(c) Torque slip characteristics of 3 ϕ induction motor.
(d) Cause of hunting and its prevention.
(e) Synchronizing an alternator with bus bars.
(f) Synchronous condensers.
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