

00402

DIPLOMA-VIEP-ELECTRICAL ENGG-V SEM

Term-End Examination

December, 2011

BIEE-035 : CONTROL SYSTEMS

Time : 2 hours

Maximum Marks : 70

Note : There are total eight questions. All questions carry equal marks. Question No. 1 is compulsory. Four questions are to be attempted out of question No 02 to 08.

1. Write 'TRUE'/'FALSE' and justify. 14
- (a) With a proportional - only controller if measurement equals set - point, the output will be 100%.
 - (b) The lowest power of 's' in the characteristic equation is called the order of the system.
 - (c) A Transfer Function relates behaviour of the input to the behaviour of the output.
 - (d) Throttling controller cannot be used as a 2 - position controller.
 - (e) The gain divided by proportional Band equals one.
 - (f) Anticipatory Control Mode can be used alone.
 - (g) Laplace Transform of $\frac{df}{dt}$ is $sF(s)$.

2. Comment on the following :
 - (a) The existence of Neutral Zone is an example of desirable hysteresis in a system. 7
 - (b) The Integral Mode is Phase - Lagging. 7

3. (a) Define an 'Electronic Controller'. Explain working of Direct-Acting and Reverse-Acting controller with one - one example. 1+3+3
- (b) Write the principle and construction of an elementary stepping motor. 3+4

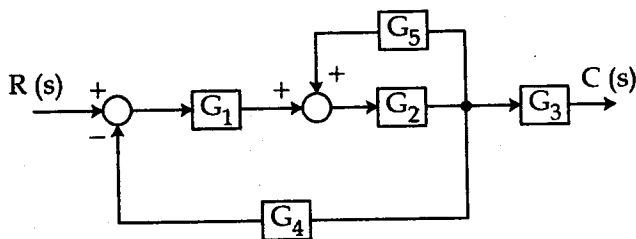
4. (a) Write two examples of Open - Loop control system and identify (by writing) the controller, the output actuator and the process for each. 3½+3½
- (b) Write the steps for drawing the Bode - Plots. 7

5. (a) Define 'stability' - what are the effects of adding pole and zero's in the root-locus. 1+6
- (b) Check the stability of the system whose characteristic equation is given by 7

$$S^4 + 2 S^2 + 6 S^2 + 4 S + 1 = 0$$

6. (a) Write the principle of operation of a position control servosystem with the help of block diagram. 7
- (b) Define Robotics and write five applications of Robotics. 2+5

7. (a) What are static error coefficients ? 7
 (b) Find the transfer function for the given block diagram shown in Fig. 1. 7



(Fig. 1)

8. Write short notes on (*any four*) : 14
- Gain Margin
 - Offset
 - Circuit diagram of ON - OFF controller using op-amp.
 - Standard Test Inputs
 - Mason's Gain Formula
 - Potentiometer as Error Detector.