

**B. Tech. VIEP ELECTRICAL
ENGINEERING (BTELVI)**

Term-End Examination

June, 2019

BIEEE-009 : DIGITAL CONTROL SYSTEM DESIGN

Time : 3 Hours

Maximum Marks : 70

Note : Attempt any five questions. Each question carries equal marks. Use of scientific calculator is allowed.

1. (a) Draw the block diagram of any closed loop control system and indicate the following on it : 7
- (i) Plant
 - (ii) Command input
 - (iii) Controlled input
 - (iv) Actuating signal
 - (v) Feedback element and control element

(A-7) P. T. O.

- (b) A unity feedback control system has a forward transfer function $\frac{25}{s(s+6)}$. Find the resonant peak for the closed loop frequency response. 7
2. (a) Write the stepwise procedure to sketch the polar plot. Suitable example can be assumed to explain. 7
- (b) Determine the stability of the system having the following characteristic equation : 7

$$2s^4 + 5s^3 + 5s^2 + 2s + 1 = 0.$$

3. (a) What are the various effects of adding a pole and a zero in the forward path for a second order system ? 7
- (b) The characteristic equation of feedback control system is :

$$s^4 + 20s^3 + 15s^2 + 2s + k = 0.$$

Determine the range of 'k' for the system to be stable. 7

4. Sketch the Bode plot for the transfer function : 14

$$G(s) = \frac{1000}{(1 + 0.1s)(1 + 0.001s)}$$

Determine the following :

- (i) Phase Margin

[3]

- (ii) Gain Margin
- (iii) Stability of System

5. For the given transfer function obtain state model : 14

$$G(s) = \frac{y(s)}{u(s)} = \frac{k}{s^3 + a_3s^2 + a_2s + a_1}$$

6. (a) What are the basic elements of an "Industrial Automatic Controller" ? 7
- (b) The closed loop transfer function is given by : 7

$$G(s) = \frac{s(s^2 + 9s + 19)}{s^3 + 7s^2 + 14s + 8}$$

determine the response of system for unit step input.

7. Write short notes on any *two* of the following :

2×7

- (a) Controllability and observability
- (b) Dead beat controller
- (c) Cascade compensators