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**BME-006** 

## B.Tech. MECHANICAL ENGINEERING (COMPUTER INTEGRATED MANUFACTURING) / B.Tech. AEROSPACE ENGINEERING (BTAE)

## **Term-End Examination**

00400

## **June, 2016**

## **BME-006 : MECHATRONICS**

Time : 3 hours

Maximum Marks: 70

- Note: Attempt any seven questions. All questions carry equal marks. Use of scientific calculator is permitted. Assume missing data, if any.
- 1. (a) Describe the working of any cam-controlled system.
  - (b) Discuss with a neat diagram how a hydraulic system can be used to amplify force. 5+5
- 2. (a) A 6-bit D/A converter gives an output voltage of 14.175 volts for an input of 011011. Determine the step size, the full range voltage, and the percentage resolution of the converter.

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- (b) What is the binary equivalent of hex 74F4? Convert that binary number into equivalent decimal and octal numbers. 5+5
- 3. (a) Identify the sensor, signal conditioner and display elements in the measurement systems of
  - (i) a mercury-in-glass thermometer, and
  - (ii) a Bourdon pressure gauge.
  - (b) Explain the difference between open-loop and closed-loop control systems. 5+5
- 4. (a) Explain the significance of the following information given in the specification of transducers:
  - (i) A piezoelectric accelerometer

Non-linearity :  $\pm 0.5\%$  of full range

(ii) A capacitive linear displacement transducer

Non-linearity and hysteresis :  $\pm 0.01\%$  of full range

 (b) Identify the various elements that might be present in a control system involving a thermostatically controlled electric heater. 5+5

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- 5. (a) Explain the function of a programmable logic controller.
  - (b) What is the difference between a thermo-couple and a thermistor? 5+5
- 6. (a) Describe four different sensing modes for photoelectric sensors.
  - (b) Discuss the basic details of
    - (i) a poppet valve, and
    - (ii) a shuttle valve.
- 7. (a) What is the non-linearity error, as a percentage of full range, produced when a  $1 k\Omega$  potentiometer has a load of  $10 k\Omega$  and is at one-third of its maximum displacement?
  - (b) A pneumatic system is operated at a pressure of 1000 kPa. What diameter cylinder will be required to move a load requiring a force of 12 kN? 5+5
- 8. (a) Explain the principle of a pilot-operated valve.
  - (b) What are the major guidelines for the selection of a sensor? 5+5

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5 + 5

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- 9. (a) Explain in brief the methods for range sensing with the help of a neat diagram.
  - (b) Describe the working of the following pumps with diagrams :
    - (i) Gear pump
    - (ii) Vane pump
- 10. (a) Compare microcomputer and microprocessor.
  - (b) What are the advantages of hydraulic system over mechanical system? 5+5

5 + 5