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**BME-006** 

## B.Tech. MECHANICAL ENGINEERING (COMPUTER INTEGRATED MANUFACTURING) / B.Tech. AEROSPACE ENGINEERING (BTAE)

## **Term-End Examination**

**June**, 2014

## **BME-006 : MECHATRONICS**

Time : 3 hours

Maximum Marks: 70

- Note: Answer any seven questions. All questions carry equal marks.
- 1. (a) Briefly explain the components of a continuous sensing system.
  - (b) A typical A/D converter has 12-bit resolution and a full range of 10 volts. What is the percent resolution and voltage resolution of this device ?
- **2.** (a) What is the difference between a thermocouple and a thermistor ?
  - (b) What is the main advantage of a capacitive proximity switch over the inductive proximity switch?

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3.	( <b>a</b> )	Describe the working of any cam-controlled system, with the help of a neat diagram.	5
	(b)	Give the advantages and disadvantages of ball screw over power screw.	5
4.	(a)	Discuss the relative advantages and disadvantages of a pneumatic system over hydraulic system.	5
	(b)	What is the difference between a positive and a non-positive displacement compressor?	5
5.	(a)	What is a 4/2 directional control valve ?	5
	(b)	With a suitable sketch, describe servo valve.	5
6.	( <b>a</b> )	Differentiate between air-amplifier and intensifier.	5
	(b)	A DC motor is running at 1500 rpm. If it is to be controlled using pulse width modulation, what duty cycle will be needed for running at 1000 rpm ?	5
7.	( <b>a</b> )	A stepper motor has a step angle of 2 degrees. If it is to be rotated at 200 rpm, what pulse rate should be given to the motor?	5
	(b)	With the help of suitable sketch describe closed loop controlled system.	5
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- 8. (a) Explain the working principle of relay with the help of a neat sketch.
  - (b) Draw and explain PLC structure and write the advantages of PLC over microcomputer.
- 9. (a) Define "Scan Time" in PLC programming.
  - (b) Construct a ladder diagram of the circuit of on/off control of lamp given as follows in Figure 1.





10. (a) Find the Laplace transform of the periodic function shown in Figure 2.



Periodic function

Figure 2

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(b) Apply the Routh – Hurwitz criterion to determine the stability of the systems whose characteristic equations are given by

(i) 
$$s^4 + 5s^3 + 2s + 10 = 0$$

(ii) 
$$s^5 - 2s^4 + 2s^3 + 4s^2 - 11s - 10 = 0$$

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