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BIEE-011

B.Tech. ELECTRICAL ENGINEERING (BTELVI)

Term-End Examination

June, 2013

BIEE-011 : ELECTRICAL MACHINES - II

Time : 3 hours

Maximum Marks : 70

Note : Answer any seven questions.

- Explain the terms coil-span factor and distribution 10 factor in connection with alternator armature windings and deduce the emf equation of an alternator incorporating the effects of these factors.
- 2. Explain the MMF method of determining the 10 voltage regulation of alternator.
- 3. Why is synchronous motor not self starting? What 10 methods are generally used to start the synchronous motors?
- Develop the equivalent circuit of a 3- phase 10 induction motor. Draw its typical torque slip characteristic and deduce the condition for maximum torque.

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- 5. (a) Discuss the pole- changing method of speed **4** control of 3 phase induction motor.
 - (b) The ratio of maximum torque to full load torque in a 3 phase squirrel cage induction motor is 2.2:1. Determine the ratio of actual torque to full load torque for the following cases
 - (i) Direct starting
 - (ii) Star-delta starting
 - (iii) Auto transformer with 70% tapping.
- Explain why single phase induction motor is not 10 self starting using double revolving field theory.
- 7. Discuss the modifications necessary to operate a 10 d.c series motor satisfactorily on a single phase a.c supply. What are the main differences in construction between a.c and d.c series motors ?
- Explain briefly the different methods of speed 10 control of 3-phase induction motors.
- Explain in detail the construction and working 10 principle of a Repulsion motor.
- 10. Write short notes on any two10
 - (a) V-curves of synchronous machines
 - (b) Stepper motor
 - (c) Parallel operation of alternators.

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