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MMTE-003

M.Sc. (MATHEMATICS WITH APPLICATIONS IN COMPUTER SCIENCE) M.Sc. (MACS)

Term-End Examination

00735

December, 2019

MMTE-003 : PATTERN RECOGNITION AND IMAGE PROCESSING

Time : 2 hours

Maximum Marks : 50

Note : Attempt any **five** questions. All questions carry equal marks. Use of calculator is **not** allowed.

1. (a) Give examples in which histogram specification is applied rather than equalization. Perform the histogram equalization on the following image :

$$\begin{bmatrix} 1 & 3 & 5 \\ 4 & 4 & 3 \\ 5 & 2 & 2 \end{bmatrix}$$

(b) Define the terms 'Entropy' and 'Coding redundancy of Huffman code'. Calculate both for the data given below :

Symbol	1	2	3	4	5	6
Huffman Code	0	10	110	1110	11110	111111
Probability	0.4	0.2	0.2	0.1	0.02	0.05

[Given $\log_2 0.05 = -4.32$]

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2. (a) A binary image X and the structuring element B are given as

	1	1	1	1	1	1				
	1	0	0	0	1	1		[1	0	1]
y –	1	0	0	0	1	1	D.		\square	
Λ-	1	1	0	0	0	1	, Б =	0	\bullet	0.
	1	1	0	0	0	1		1	0	1
	1	1	1	1	1	1				

- (i) Find X^c , $X \oplus B$, $X^c \ominus B$, $X \ominus B$ and $X^c \oplus B$.
- (ii) Find the relationship between $X \Theta B$ and $X^{c} \oplus B$.

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- (b) What is the relevance of determining the Laplacian of an image ? Show that subtracting the Laplacian of an image from the image itself is proportional to unsharp masking.
- 3. (a) Compute Mean Square Error (MSE) and Signal to Noise Ratio (SNR) for the reference image f(x, y) and processed image $\hat{f}(x, y)$ where

$$\mathbf{f}(\mathbf{x}, \mathbf{y}) = \begin{bmatrix} 3 & 2 & 4 \\ 4 & 2 & 4 \\ 3 & 2 & 2 \end{bmatrix} \text{ and } \hat{\mathbf{f}}(\mathbf{x}, \mathbf{y}) = \begin{bmatrix} 3 & 1 & 1 \\ 2 & 1 & 2 \\ 2 & 2 & 1 \end{bmatrix}_{5}$$

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(b) What is Discrete Fourier Transform(DFT) ? Find DFT to the sequence (x) given below :

 $X = \{1 2 3 4\}$

Also, find Inverse Discrete Fourier Transform.

- 4. (a) What is Digital Image Watermarking ? Write the steps involved in the process of watermark embedding and extraction through suitable block diagram.
 - (b) What is the difference between the terms Bandpass and Bandreject filters, in context of their utility in Digital Image processing?
 Determine the equation for the Bandpass filters corresponding to the Bandreject filters given below :

(i) Ideal:

$$H(u, v) = \begin{cases} 0 & \text{if } D_0 - \frac{W}{2} \le D \le D_0 + \frac{W}{2} \\ 1 & \text{otherwise} \end{cases}$$

(ii) Gaussian:

$$H(\mathbf{u}, \mathbf{v}) = 1 - e \left[\frac{D^2 - D_0^2}{DW} \right]^2$$

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5. (a) What is linear convolution ? How is it different from linear correlation ? Perform the linear convolution between two matrices X(m, n) and h(m, n) given below :

$$X(\mathbf{m}, \mathbf{n}) = \begin{bmatrix} 3 & 1 \\ 2 & 4 \end{bmatrix} \text{ and } \mathbf{h}(\mathbf{m}, \mathbf{n}) = \begin{bmatrix} 1 & 5 \\ 2 & 3 \end{bmatrix}$$

Also obtain the linear correlation between the matrices X(m, n) and h(m, n). Finally, comment on the result obtained.

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(b) What is Bayesian classification ? How is it different from clustering ? Apply the Bayesian classifier to predict the class of (2, 2) from the dataset given below :

a ₁	2	0	2	0	3
a ₂	0	2	4	2	2
Class (i)	c ₁	c ₁	c_2	с ₂	c_2

Assume that both the classes follow multivariate normal density function.

6. (a) Use the Naive Bayes classifier and classify the unknown pixel X in the image shown below :

#	#	#	*]
#	X	#	*
#	#	*	*
#	#	*	*

where # and * are two different classes of pixels present in the image. Consider the 8 - neighbourhood of X and determine the class of X.

	r ma	UIR	e r
ļ	2	3	4
	1	2	4
	2	3	2

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(b) Find the resultant image if the image $\begin{bmatrix} 2 & 3 & 4 & 5 \end{bmatrix}$

is	filtered	hv 2	a M'	in fi	lter	with	а	mask	L	
10	monica	<i>v</i> , .	~							

7. (a) List three properties of a median filter.

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- (b) Using 0, 1 and -1 as coefficient values, give the form for eight operators that measure gradient of edges oriented in eight directions : E, NE, N, NW, W, SW, S and SE. Specify the gradient direction of each mask.
- (c) Define principal component analysis with example.

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