Time: 3 Hoursl

*Note* : (i)

**BME-006** 

1.

**BME-006** 

[Maximum Marks: 70]

P.T.O.

## B.Tech. MECHANICAL ENGINEERING (COMPUTER INTEGRATED MANUFACTURING)/B.Tech. AEROSPACE ENGINEERING (BTAE)

## Term-End Examination,

## December 2019

## **BME-006: MECHATRONICS**

(i) Answer any seven questions.(ii) All questions carry equal marks.

(iii) Use of scientific calculator is permitted.

a) What is the difference between a thermocouple and

	b)	a thermistor? 5 What is the main advantage of a capacitive proximity switch over the inductive proximity switch? 5
2.	a)	Describe the working of any cam-controlled system
	b)	with the help of a neat diagram. 5 Give the advantages and disadvantages of ball screw over power screw. 5
3.	a)	Explain the working principle of relay with the help of a neat sketch.
	b)	Draw and explain PLC structure and write the advantages of PLC over microcomputer. 5
4.	a)	Differentiate between open-loop and closed-loop control system.

- b) Apply the Routh-Hurwitz criterion to determine the stability of the systems whose characteristic equations are given by:

  5
  - i)  $s^4 + 4s^3 + 2s + 15 = 0$
  - ii)  $s^5 2s^4 + 3s^3 + 5s^2 10s 15 = 0$
- 5. a) A 6-bit D/A converter gives an output voltage of 12.15 V for an input of 011011. What is the step size, the full range voltage and the percentage resolution?
  - b) Determine the binary equivalent of (231)<sub>8</sub>. 5
- 6. a) Identify the sensor, signal conditioner and display elements in the measurement system of a mercury-in-glass thermometer. 5
  - b) Identify the various elements that might be present in a control system involving a thermostatically controlled electric heater.
- 7. a) What are the two types of data transfer techniques used in computer interfacing? List out the main differences between them.
  - b) What do you mean by inverse kinematics? Briefly explain the importance of path planning. 5
- 8. Write short notes on any five of the following:  $5\times2=10$ 
  - a) Amplifier

b) Accumulator

c) Actuators

d) Diode

e) Robot

f) Tactile sensing

g) Accuracy

h) •Modem

