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BME-056

DIPLOMA IN MECHANICAL ENGINEERING (DME) / ADVANCED LEVEL CERTIFICATE COURSE IN MECHANICAL ENGINEERING (DMEVI / ACMEVI)

Term-End Examination

BME-056 : THEORY OF MACHINES

Time : 2 hours

Maximum Marks : 70

Server End Co.

Note : Answer any **five** questions. All questions carry equal marks. Assume missing data suitably. Use of scientific calculator is allowed.

1. Explain any *four* of the following terms : $4 \times 3\frac{1}{2} = 14$

- (a) Instantaneous centre
- (b) Law of gearing
- (c) Rolling friction
- (d) Involute profile of gear teeth
- (e) Hammer blow
- 2. Explain Whitworth Quick Return Mechanism with a sketch. Discuss its application in shaper machines.

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- 3. Describe the following types of pairs with sketches according to nature of relative motion: $4 \times 3 \frac{1}{2} = 14$
 - (a) Sliding pair
 - (b) Turning pair
 - (c) Rolling pair
 - (d) Screw pair
- 4. Describe the working of the following types of cams: $4 \times 3 \frac{1}{2} = 14$
 - (a) Wedge and flat cams
 - (b) Radial or disc cams
 - (c) Spiral cams
 - (d) Spherical cams
- 5. Derive the efficiency of a square threaded screw? Also prove that the maximum efficiency is given by the equation

$$\mathbf{e}_{\max} = \frac{1 - \sin \phi}{1 + \sin \phi},$$

where ϕ represents the friction angle.

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- 6. The turning moment diagram for я multi-cylinder engine has been drawn to a vertical scale of 1 mm = 650 Nm and a horizontal scale of $1 \text{ mm} = 4.5^{\circ}$. The areas above and below the mean torque line are -28, +380, -260, +310, -300, +242, -380, +265 and -229 mm². The fluctuation in speed is limited to $\pm 1.8\%$ of the mean speed which is 400 rpm. Density of the rim material is 7000 kg/m^3 and width of the rim is 4.5 times its thickness. The centrifugal stress (hoop stress) in the rim material is limited to 6 N/mm^2 . Neglecting the effect of the boss and arms, determine the diameter and cross-section of the flywheel rim.
- 7. Write short notes on any *two* of the following : $2 \times 7 = 14$
 - (a) Logarithmic Decrement
 - (b) Gyroscope
 - (c) Dynamic Balancing
 - (d) Dynamometer

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