

**B.Tech. (AEROSPACE ENGINEERING)
(BTAE)**

Term-End Examination

00433 December, 2018

BAS-020 : BASIC CONTROL THEORY

Time : 3 hours

Maximum Marks : 70

Note : Attempt any five questions. All questions carry equal marks. Use of scientific calculator is permitted.

1. (a) Determine the stability of the system whose characteristic equation is given by

$$2\lambda^3 + 4\lambda^2 + 4\lambda + 12 = 0. \quad 6$$

- (b) Differentiate between the following : $2 \times 4 = 8$
- (i) Classical and Modern Control theories
 - (ii) Stable and Unstable systems

2. (a) Given the 4th order characteristic equation

$$\lambda^4 + 6\lambda^3 + 11\lambda^2 + 6\lambda + k = 0.$$

For what value of k will the system be stable ?

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- (b) Describe in brief the PID Controller.

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3. Given the loop transfer function

$$G(s) H(s) = \frac{k}{s(s + 3)(s + 10)}.$$

- (a) Sketch root locus plot for $G(s) H(s)$.
- (b) Add a simple pole, $(s + 2)$, to $G(s) H(s)$ and examine the resultant root locus.
- (c) Add a simple zero, $(s + 2)$, to $G(s) H(s)$ and examine the resultant root locus.

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4. Define the following :

7×2=14

- (a) Transfer function
- (b) Poles and zeroes
- (c) Routh's criterion
- (d) Root locus plot
- (e) Compensator
- (f) Gain and Phase margin
- (g) Closed loop system

5. Write short notes on any **two** of the following : $2 \times 7 = 14$

- (a) Stability Augmentation
- (b) Synchros
- (c) Autopilot
- (d) Sensors

6. (a) The single degree of freedom pitching motion of an airplane was shown to be represented by a second-order differential equation. The equation is given as

$$\ddot{\theta} + 0.5 \dot{\theta} + 2 \theta = \delta_e$$

where θ and δ_e are in radians.

Estimate the time rise, peak overshoot and settling time for step input of the elevator angle of 0.1 rad.

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- (b) Define peak overshoot and settling time. 4
7. (a) Write a note on 'Computer Electronic Design Aspects'. 5
- (b) Explain forward path compensation with the help of an example. 4
- (c) Explain 'Roll Altitude Autopilot' with the help of an example. 5
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