00362

B.Tech. (AEROSPACE ENGINEERING) (BTAE)

Term-End Examination December, 2017

BAS-020: BASIC CONTROL THEORY

Tim	e:3 h	ours Maximum Marks : 70
		 (i) Attempt any seven questions. (ii) All questions carry equal marks. (iii) Use of scientific calculator is permitted.
1.	(a)	Explain the requirements of an automatic 3 control system.
	(b)	Explain the various elements of an 4 automatic feedback control system.
	(c)	Distinguish between classical and modern control theory.
2.	(a)	Explain dynamics of a stable and unstable 6 system with the help of examples.
	(b)	Explain the importance of Laplace 4 Transforms in control theory.
3.	(a)	Explain the standard test signals with the 3 help of diagrams.
	(b)	Explain the factors affecting the 7 performance of control system.

Explain the following transient response 4. specifications with the help of a plot. 5x2=10Delay time (a) Rise time (b) (c) Peak time (d) Settling time (e) Steady state error 5. How control action is decided in case of a feedback control system? Explain PI and PID controller with the help of examples. 2+8=10 6. Write notes on the following: 5+5=10 (a) BODE plot Modelling of DC motor (b) Determine the stability of the following cases. 7. Which represent characteristic equations of two different control systems: 5+5=10 $3s^4 + 10s^3 + 5s^2 + 5s + 2 = 0$ (a) (b) $\lambda^3 + 6\lambda^2 + 12\lambda + 8 = 0$ (a) Explain the rules for graphical construction 8. 5 of the root locus plot. (b) Sketch the root locus plot for the 5 following transfer function. G (s) H (s) = $\frac{k (s+3)}{s (s+10) (s^2 + 8s + 20)}$ Explain the following: 9.

5x2=10

- Gain and phase margin (a)
- (b) Compensator
- (c) Stability margin
- (d) Transport delay
- Actuator (e)