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**BIELE-011** 

## B.Tech. – VIEP – ELECTRONICS AND COMMUNICATION ENGINEERING (BTECVI)

## **Term-End Examination**

December, 2016

2000

## **BIELE-011 : DIGITAL SYSTEM DESIGN**

Time : 3 hours

Maximum Marks : 70

**Note :** Attempt any **seven** questions. All questions carry equal marks. Use of scientific calculator is allowed.

- 1. Draw the logic diagram of a 4-bit look ahead carry adder and calculate the speed-up compared to a 4-bit binary ripple adder.
- 2. Reduce the state diagram shown in Figure 1 and also write the reduced state table. Consider the input sequence as "01010110100" starting from the initial condition '0'.



Figure 1

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 Design the controller whose state diagram is shown in Figure 2. Write the RTL model of the controller.



Figure 2

4. Implement the Boolean function

 $F(A, B, C, D) = \sum m(0, 2, 5, 7, 11, 14)$  and

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$$P(A, B, C, D) = \prod M(1, 4, 5, 7, 9, 12, 15)$$

with multiplexer.

- 5. Write the working principle of ROM matrix for implementing a truth table of a full subtractor. 10
- 6. (a) Differentiate between Synchronous state machine and Asynchronous state machine.
  - (b) Design a Mod-6 up counter using J-K flip-flop.

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- 7. Explain the types of operators in VHDL design. Write a program for a 4-bit binary to BCD conversion using data flow model.
- 8. Draw a multilevel NOR and multilevel NAND gate circuit to implement the Boolean function  $F(A, B, C, D, E) = (\overline{AB} + \overline{CD})E + \overline{BC} (A + B).$
- 9. Write the data flow description for a 4-bit comparator. The output of the comparator is '1' when both the inputs are unequal and is '0' for equal input.
- 10. Design a logic circuit that controls an elevator in a four-storied building. The circuit has two inputs for user to indicate the desired floor to reach. The lift starts moving when start input = 1. M is an output signal that indicates if the desired floor is reached (i.e., M = 1) and stops the lift for opening of gate. 'M' remains in low state (i.e., '0'), when the lift is moving.  $F_1$  and  $F_2$  are two outputs to show the floor level that the lift has reached.

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