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BIEL-008

B.Tech. – VIEP – ELECTRONICS AND COMMUNICATION ENGINEERING (BTECVI)

Term-End Examination December, 2015

BIEL-008: MICROCONTROLLERS

Time: 3 hours Maximum Marks: 70

Note: Attempt any **seven** questions. All questions carry equal marks.

- 1. (a) Describe the evolution of 8051 microcontroller.
 - (b) Explain the microcontroller with the help of a neat block diagram. $2\times5=10$
- 2. (a) Compare and contrast the RISC processor with the CISC processor.
 - (b) Compare and contrast a microprocessor system with microcontroller system. $2\times5=10$
- 3. (a) Explain how a memory can be accessed by using various addressing modes.
 - (b) What are the advantages of register indirect addressing mode? $2\times5=10$

4. Assume that 5 BCD data items are stored in RAM locations starting at 40H, as shown below. Write a program to find the sum of all the numbers. The result must be in BCD.

10

$$40 = (71)$$

$$41 = (11)$$

$$42 = (65)$$

$$43 = (59)$$

$$44 = (37)$$

- **5.** (a) Explain the conditions that determine each conditional jump instructions.
 - (b) What is the function of each of the following commands?
 - (i) JZ
 - (ii) JNC
 - (iii) LJMP

 $2 \times 5 = 10$

- 6. (a) Discuss the reason for writing a program in C for 8051 microcontroller.
 - (b) What are the various datatypes in C for 8051? $2\times5=10$

- 7. (a) Write a program to transfer a letter 'Y' serially at 9600 baud continuously, and also send a letter 'N' through port 0, which is connected to the display device.
 - (b) Discuss the importance of TI flag. $2\times5=10$
- **8.** (a) Describe the various types of interrupts used in 8051 microcontroller.
 - (b) Discuss the advantages of interrupt based data transfer. $2\times 5=10$
- 9. (a) Explain how data can be transferred to the LCD from a port using only 4 port lines.
 - (b) What are the various control pins of LCD? Also explain their functions. $2\times 5=10$
- 10. Write short notes on any **two** of the following: $2\times5=10$
 - (a) Harvard and Von Neumann CPU
 - (b) Data Serialization
 - (c) Stepper Motor Interfacing