BIMEE-013

B.Tech. MECHANICAL ENGINEERING (BTMEVI)

Term-End Examination December, 2013

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051				
õ	BIM	EE-013 : FINITE ELEMENT ANALYSIS		
Time	e : 3 h	ours Maximum Marks	Maximum Marks : 70	
Note	e: (i (i (i) Answer any five questions. i) Scientific calculator is allowed . ii) All questions carry equal marks.		
1.	(a) (b)	Write a note on variational functions. What is connectivity in finite element Models ?	4 4	
	(c)	Compare the formulation of one dimensional finite element problems using two-node linear elements versus three node quadratic elements.	6	
2.	An axial load $P = 400 \times 10^3$ N is applied at 20°C to the rod as shown in figure 1. The temperature is then raised to 60°C Determine the element stresses.		14	
		$-200 \longrightarrow -300 \longrightarrow P$ $A = 2$ $B = 3$		
	E _A = E _B =	Figure - 1 = $70 \times 10^9 \text{ N/m}^2$ = $200 \times 10^9 \text{ N/m}^2$ = $900 \text{ mm}^2 \text{ A} = 1200 \text{ mm}^2$		

 $A_{A}^{2} = 900 \text{ mm}^{2}, A_{B} = 1200 \text{ mm}^{2}$ $\alpha_{A} = 23 \times 10^{-6} \text{ per}^{\circ}\text{C}$ $\alpha_{B} = 11.7 \times 10^{-6} \text{per}^{\circ}\text{C}.$

BIMEE-013

3. Compute the reactions for the beams shown in 14 Figure 2.



- 4. Assume a uniform section rod of elastic material 14 fixed at both ends and 3L long with uniform body force loading F. Use three linear elements of length 'L' and formulate the Rayleigh-Ritz solution using shape functions rather than interpolation formulas.
- 5. (a) Distinguish between a truss and frame.
 - (b) Three springs are assembled colinear as shown in figure 3. Nodes 1 and 4 fixed and axial loads of 10 kN and 20 kN are applied at node 2 and 3 respectively. Determine the displacement at node 2 and 3.

7

7

6. (a) Describe what are shape functions ?

(b) A set of springs connected together as shown in figure 4 is subjected to axial loads of 10 kN, 20 kN at node points 1 and 4. Determine the displacements as node 1,2 and 4.



5

9

7. Derive the transformation matrix and 14 corresponding stiffness matrix for a beam oriented in a local ξ , η coordinate system and referenced to the global *x*, *y* coordinate system.