

B.Tech. IN ELECTRICAL ENGINEERING

Term-End Examination

December, 2013

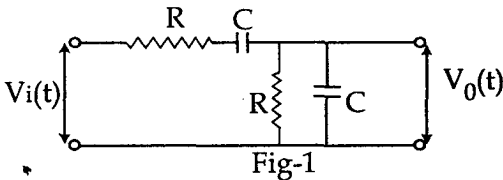
BIEE-021 : CONTROL SYSTEM

Time : 3 hours

Maximum Marks : 70

Note : Attempt any five questions. Each question carry equal marks. Use of scientific calculator and graph papers are permitted.

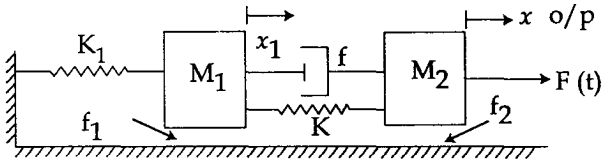
1. (a) Find the transfer function of the network shown in fig. 1. Plot its poles and zeros for $R=C=1$. 7



- (b) Draw signal flow graph for the equation 7

$$\frac{d^2y}{dx^2} + \frac{2}{3} \frac{dy}{dx} + \frac{11}{2}y = x$$

2. (a) Obtain the transfer function of the mechanical system shown in fig.2. 7



- (b) Are the two systems given in fig.3(a),(b) equivalent. If not then prove so : 7

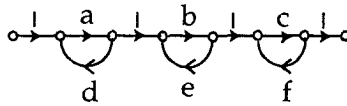


Fig-3(a)

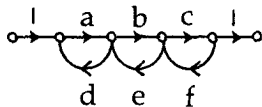


Fig-3(b)

3. (a) A unity FB system is characterised by an open loop transfer function $G(S) = \frac{K}{S(S+10)}$. 7

Determine Gain K so that $\xi = 0.5$. Also determine t_s , M_p and t_p for a unit step input.

- (b) Differentiate between : 7
- Open loop and closed loop control system.
 - Regulator and tracking control

4. Determine the open loop transfer function of a system whose approximate plot is shown in fig.4. 14

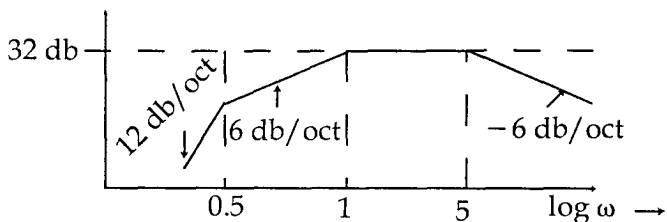


Fig - 4

5. Consider a matrix A given below find the eigen values, eigen vector, modal matrix and diagonalise it. 14

$$A = \begin{pmatrix} 0 & 1 & 0 \\ 3 & 0 & 2 \\ -12 & -7 & -6 \end{pmatrix}$$

6. Write short note on following : 2x7=14
- (a) Frequency domain specifications
 - (b) Routh-Hurwitz stability criteria
7. (a) Sketch the polar plot of $G(S) = \frac{1}{S(1+ST)}$. 7
- (b) Determine the range of K such that 7
feedback system having characteristic
equation
 $S(S^2 + S + 1)(S + 4) + K = 0$
8. Define *any four* of the following : 4x3.5=14
- (a) Gain Margin and Phase Margin
 - (b) PID Controller
 - (c) Synchros
 - (d) Mason's Gain Formula
 - (e) Pneumatic Controller
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