No. of Printed Pages: 3

BIEE-019

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B.TECH. - ELECTRICAL ENGINEERING

Term-End Examination December, 2013

BIEE-019: ELECTRICAL INSTRUMENTATION

Time: 3 hours Maximum Marks: 70

Note: Attempt any five questions.

All questions carry equal marks.

- 1. (a) Distinguish between:
 - (i) Active and passive transducers.
 - (ii) Input and output transducers. Illustrate your answer with suitable example.
 - (b) A force of δ newton is impressed upon a piezo-electric crystal having dimension of $6 \text{ mm} \times 6 \text{ mm} \times 1.5 \text{ mm}$ thick. For the crystal materials, charge sensitivity = 140×10^{-12} C/N, Primitivity = 12×10^{-9} N/m and modulus of elasticity = 11.5×10^6 N/m². Make calculation for the capacitance.
- 2. (a) Explain the major consideration which 7 govern the selection of an instrument transducer. List some advantages of electrical transducers over mechanical transducers.
 - (b) Differentiate between a bridge, operated on the null principle and a bridge, operated on the deflection principle.

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A resistance of 2 ohms has been measured (a) 3. 10 by using a null type wheatstone bridge circuit. If the accuracy of bridge ratio is ±0.05% and that of variable resistor R₂ is ±0.025%. Calculate the possible error in the measurement of resistance of 2 ohm. (b) Write short note on LVDT. 4 4. (a) Define modulation and demodulation. 7 Describe the operation of amplitude modulation and frequency modulation system. (b) Mention the different recording instruments 7 and describe the operation of an ultraviolet recorder. Describe the operation of cistern (Single 7 5. (a) Column) manometer and inclined tube manometer. Derive the relationship between the input and the output in each case. 7 (b) What is the case compensation and the full compensation in a filled-in-system? What is the bulb elevation error in a filled-in-system? Is it larger in a gas-filled-system than in a liquid-filled-system? 6. Mention different techniques available for 7 (a) the measurement of strain and explain the principle on which the operation of an electrical resistance strain gauge is based. Give several examples of digital methods of 7 (b)

angular velocity measurement. Sketch and explain the operation of any one of them.

7. (a) The deviation change of certain integral controller has a sinusoidal variation with time. Workout the phase difference between the manipulated variable and the deviation.

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- (b) Write short notes on:
 - (i) Fibre optic transducers.
 - (ii) Spectrum analyzer.

BIEE-019

