

**B.Tech. IN ELECTRONICS AND  
COMMUNICATION ENGINEERING  
(BTECVI)**

00491

**Term-End Examination**

**December, 2012**

**BIEL-007 : SIGNALS AND SYSTEMS**

*Time : 3 hours**Maximum Marks : 70*

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*Note : Attempt any seven questions.*

*All questions carry equal marks. Use of Scientific calculator is allowed.*

*All the questions are to be answered in English Language only.*

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1. Determine whether or not the signals below are periodic and for each signal that is periodic, determine the fundamental period : 10

(a)  $x(t) = 2\sin\left(\frac{2}{3}\right)t + 3\cos\left(\frac{2\pi}{5}\right)t$

(b)  $x(t) = \cos t + \sin(\sqrt{2})t$

(c)  $x(n) = 2\sin(0.8\pi n)$

(d)  $x(n) = 1 + e^{(j4\pi n)/7} + e^{(j2\pi n)/5}$

(e)  $x(t) = 2\cos(10t + 1) - \sin(4t - 1)$

2. (a) Compare Energy and Power signals ? 5  
 Determine the condition of periodicity for continuous time signals.

(b) A continuous time signal  $x(t)$  is shown in Fig.1. Sketch and label each of the following signals. 5

(i)  $x(t-2)$

(ii)  $x(2t)$

(iii)  $x\left(\frac{t}{2}\right)$

(iv)  $x(-t)$

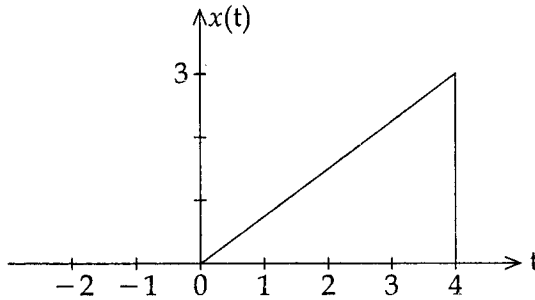


Fig. 1

3. (a) Consider a LTI system with input and output related through the following equation 5

$$y(t) = \int_{-\infty}^t e^{-(t-\tau)} x(\tau-2) d\tau$$

What is the impulse response  $h(t)$  for this system.

(b) Show that the convolution of two odd functions is an even function. 5

4. Determine whether the following systems are static or dynamic, Linear or non-linear. Shift variant or invariant, non-causal or causal, stable or unstable. 10

(a)  $y(t) = x(t + 10) + x^2(t)$

(b)  $y(n) = x(n)u(n)$

(c)  $y(n) = \text{sgn}[x(n)]$

(d)  $y(n) = \text{Trunc}[x(n)]$

(e)  $y(n) = \sum_{K=-\infty}^{n+1} x(K)$

5. (a) Consider a causal LTI system with frequency response  $H(\omega) = \frac{1}{3 + j\omega}$ . 5

$$H(\omega) = \frac{1}{3 + j\omega}$$

For a particular input  $x(t)$ , this system is observed to produce the output

$$y(t) = e^{-3t}u(t) - e^{-4t}u(t)$$

Determine  $x(t)$ .

- (b) Find the Fourier transform of the following : 5

$$x(t) = \begin{cases} \frac{t}{b-a} + \frac{b}{b-a}, & \text{for } -b < t < -a \\ 1, & \text{for } -a < t < a \\ \frac{b}{b-a} + \frac{t}{b-a}, & \text{for } a < t < b \end{cases}$$



6. Determine the system Transfer function  $H(z)$  and the frequency response of the system whose impulse response is given as 10

$$h(n) = \left(\frac{1}{2}\right) \left[ \left(\frac{1}{2}\right)^n + \left(-\frac{1}{4}\right)^n \right] u(n)$$

Also locate zeros and poles in Z-plane.

7. Determine the inverse Z-Transform of the function 10

$$X(Z) = \frac{Z - 1}{Z^2 - 4Z + 4}$$

8. Find the Z-transform of the following discrete-time signal. Also determine the ROC for each of the following cases : 10

(a)  $S(n) = 2^n u(n) + 3 \left(\frac{1}{2}\right)^n u(n)$

(b)  $S(n) = 3 \left(\frac{-1}{2}\right)^n u(n) - 2(3)^n u(-n - 1)$

9. For the DT system described by the following difference equation. 10

$$y(n] = 0.6y(n - 1) - 0.08y(n - 2) + x(n)$$

Determine :

- (a) The unit-sample response sequence,  $h(n)$   
(b) The step-response sequence  $g(n)$   
(c) Whether it is BIBO stable

10. Write short notes on *any two* :

5x2=10

- (a) Classification of signals.
  - (b) Linear time Invariant (LTI) system.
  - (c) Region of Convergence (ROC).
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